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What is clear is that if you want to control a system, you need to know what you want it to do, and you need to know how well it is doing. That implies a couple of things. First, you need to know what you want the system to do.

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Control Engineering Problems with Solutions 10 Mathematical Models and Block Diagrams
The first set of examples will be concerned with model representations for a single block. The transfer function of a component, assumed to behave linearly, is the Laplace transform of its linear constant

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Control syst,r,m with reference input and disturbance input. Solution. First move the branch point between G, and G4 to the right-hand side of the loop containing G,, G,, and H,. Then move the summing point between GI and C, to the left-hand side of the first summing point. See Figure 3-47(a). By simplifying each loop, the block diagram can

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